Particle system with random interaction

Xavier Erny

Ecole Polytechnique (CMAP)

Journée francilienne d'accueil des postdoctorant·e·s Institut Henri Poincaré, 20 October 2021

Introduction

- Particle systems
- Point processes
- Mathematical model

2 Large scale limits for particle systems

- Large scale limit
- Linear scaling

3 Generalization

- McKean-Vlasov frame
- Multi-population system

Particle systems Point processes Mathematical mode

Particle systems

Particle system :

▶ < ∃ > 3 / 21 æ

Particle systems Point processes Mathematical mode

Particle systems

Particle system :

• collection of interacting particles of same kind.

< ≣ ► 3/21 э

Particle systems Point processes Mathematical mode

Particle systems

Particle system :

- collection of interacting particles of same kind. Ex :
 - particles in motion

э

Particle systems Point processes Mathematical mode

Particle systems

- collection of interacting particles of same kind. Ex :
 - particles in motion
 - neural network [Löcherbach, Ditlevsen (2017)],...

Particle systems Point processes Mathematical mode

Particle systems

- collection of interacting particles of same kind. Ex :
 - particles in motion
 - neural network [Löcherbach, Ditlevsen (2017)],...
 - gene network [Reynaud-Bouret, Schbath (2010)],...

Particle systems Point processes Mathematical mode

Particle systems

- collection of interacting particles of same kind. Ex :
 - particles in motion
 - neural network [Löcherbach, Ditlevsen (2017)],...
 - gene network [Reynaud-Bouret, Schbath (2010)],...
 - inter-gang crimes [Stomakhin et al. (2011)]

Particle systems Point processes Mathematical mode

Particle systems

Particle system :

- collection of interacting particles of same kind. Ex :
 - particles in motion
 - neural network [Löcherbach, Ditlevsen (2017)],...
 - gene network [Reynaud-Bouret, Schbath (2010)],...
 - inter-gang crimes [Stomakhin et al. (2011)]

• each particle has a state

Particle systems Point processes Mathematical mode

Particle systems

- collection of interacting particles of same kind. Ex :
 - particles in motion
 - neural network [Löcherbach, Ditlevsen (2017)],...
 - gene network [Reynaud-Bouret, Schbath (2010)],...
 - inter-gang crimes [Stomakhin et al. (2011)]
- each particle has a state
- each state follows a dynamic
 - (ex : differential equation, ODE, PDE, SDE, SPDE...)

Particle systems Point processes Mathematical mode

Discrete time interaction

Frame modelization :

æ

E ► < E ►</p>

< □ > < / >

Particle systems Point processes Mathematical mode

Discrete time interaction

Frame modelization :

• each particle "creates" event at random rate

э

Particle systems Point processes Mathematical mode

Discrete time interaction

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

Particle systems Point processes Mathematical mode

Discrete time interaction

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

Particle system	One particle	Events

Particle systems Point processes Mathematical mode

Discrete time interaction

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

Particle system	One particle	Events
Neural network	Neuron	Spike emitting

Particle systems Point processes Mathematical mode

Discrete time interaction

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

Particle system	One particle	Events
Neural network	Neuron	Spike emitting
Gene network	Gene	Proteins emitting

Discrete time interaction

Frame modelization :

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

Particle system	One particle	Events
Neural network	Neuron	Spike emitting
Gene network	Gene	Proteins emitting
Inter-gang crimes	Pair of gangs	Violent crimes

E 900

Discrete time interaction

Frame modelization :

- each particle "creates" event at random rate
- each event modifies the rate of all the particles (Excitation/Inhibition)

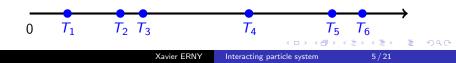
Particle system	One particle	Events
Neural network	Neuron	Spike emitting
Gene network	Gene	Proteins emitting
Inter-gang crimes	Pair of gangs	Violent crimes

The activity of each particle is modeled by a point process

Particle systems Point processes Mathematical model

Point process : definitions

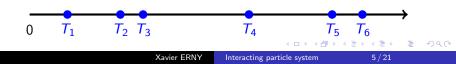
- A point process Z is :
 - a random countable set of \mathbb{R}_+ : $Z = \{T_n : n \in \mathbb{N}\}$



Particle systems Point processes Mathematical model

Point process : definitions

- A point process Z is :
 - a random countable set of \mathbb{R}_+ : $Z = \{T_n : n \in \mathbb{N}\}$
 - a random point measure on \mathbb{R}_+ : $Z = \sum_{n \in \mathbb{N}} \delta_{T_n}$

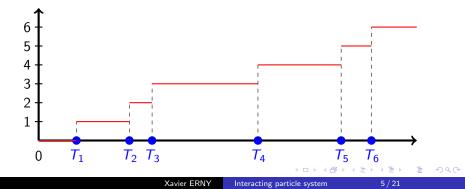


Particle systems Point processes Mathematical model

Point process : definitions

A point process Z is :

- a random countable set of \mathbb{R}_+ : $Z = \{T_n : n \in \mathbb{N}\}$
- a random point measure on \mathbb{R}_+ : $Z = \sum_{n \in \mathbb{N}} \delta_{T_n}$
- a stair function on \mathbb{R}_+ : $Z_t = Z([0, t])$



Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

Non-constant rate $(\lambda_t)_{t\geq 0}$:

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

 \mathcal{T}_1 exponential variable with parameter λ

Non-constant rate $(\lambda_t)_{t\geq 0}$:

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

 \mathcal{T}_1 exponential variable with parameter λ

Non-constant rate $(\lambda_t)_{t\geq 0}$: [Lewis, Schedler (1979)], [Ogata (1981)]

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

 \mathcal{T}_1 exponential variable with parameter λ

Non-constant rate $(\lambda_t)_{t\geq 0}$: [Lewis, Schedler (1979)], [Ogata (1981)]

• define \mathcal{T}' exponential variable with parameter $||\lambda||_{\infty}$

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

 \mathcal{T}_1 exponential variable with parameter λ

Non-constant rate $(\lambda_t)_{t\geq 0}$: [Lewis, Schedler (1979)], [Ogata (1981)]

• define T' exponential variable with parameter $||\lambda||_{\infty}$

• then
$$\begin{cases} \text{ with probability } \lambda_{T'}/||\lambda||_{\infty}, T_1 := T \\ \text{ otherwise, repeat from } T' \end{cases}$$

Rate of events

Context : consider Z point process with rate λ **Problem** : define T_1 the 1st atom of Z

Solution :

Constant rate $\lambda \in \mathbb{R}^*_+$:

 \mathcal{T}_1 exponential variable with parameter λ

Non-constant rate $(\lambda_t)_{t\geq 0}$: [Lewis, Schedler (1979)], [Ogata (1981)]

Why: Let Z point process with constant rate $\lambda > 0$, and $t \ge 0, n \in \mathbb{N}^*$ Conditionally to $\{Z_t = n\}$, the T_k $(1 \le k \le n)$ are iid uniform on [0, t]

6/21

Introduction Particle Large scale limits for particle systems Generalization Mather

Particle systems Point processes Mathematical model

Mathematical model

Let us consider a N-particle system :

• each particle creates events

< ≣ ► 7 / 21 э

Particle systems Point processes Mathematical model

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*
- $Z^{N,i}$ has rate $f(X_t^{N,i})$

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*
- $Z^{N,i}$ has rate $f(X_t^{N,i})$

Dynamic of $X^{N,i}$:

$$dX_t^{N,i} = b\left(X_t^{N,i}\right) dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*
- $Z^{N,i}$ has rate $f(X_t^{N,i})$

Dynamic of $X^{N,i}$:

$$dX_t^{N,i} = b\left(X_t^{N,i}\right) dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Interpretation :

< ∃ →

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*
- $Z^{N,i}$ has rate $f(X_t^{N,i})$

Dynamic of $X^{N,i}$:

$$dX_t^{N,i} = b\left(X_t^{N,i}\right) dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Interpretation :

• while no event occurs, the dynamic is an ODE

Mathematical model

Let us consider a N-particle system :

- each particle creates events
- $Z_t^{N,i}$ = number of events of particle *i* before *t*
- $Z^{N,i}$ has rate $f(X_t^{N,i})$

Dynamic of $X^{N,i}$:

$$dX_t^{N,i} = b\left(X_t^{N,i}\right) dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Interpretation :

- while no event occurs, the dynamic is an ODE
- if particle j creates event at time t, $X_t^{N,i} = X_{t-}^{N,i} + u(j,i,t)$

Particle systems Point processes Mathematical model

Neural network model

• particle = neuron

$$dX_t^{N,i} = b(X_t^{N,i})dt + \sum_{j=1}^N u(j,i,t)dZ_t^{N,j}$$

æ

< ロ > < 回 > < 回 > < 回 > < 回 >

Introduction Large scale limits for particle systems Generalization Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike

$$dX_t^{N,i} = b(X_t^{N,i})dt + \sum_{j=1}^N u(j,i,t)dZ_t^{N,j}$$

Image: A mathematical states and a mathem

э

'문▶' ★ 문≯

Introduction Particle Large scale limits for particle systems Generalization Mathem

Particle systems Point processes Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike
- $X^{N,i}$ = membrane potential of the neuron *i*

$$dX_t^{N,i} = b(X_t^{N,i})dt + \sum_{j=1}^N u(j,i,t)dZ_t^{N,j}$$

Introduction Particle Large scale limits for particle systems Generalization Mather

Particle systems Point processes Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike
- $X^{N,i}$ = membrane potential of the neuron *i*

$$dX_t^{N,i} = \frac{b(X_t^{N,i})}{b(X_t^{N,i})}dt + \sum_{j=1}^N u(j,i,t)dZ_t^{N,j}$$

Introduction Particle Large scale limits for particle systems Generalization Mather

Particle systems Point processes Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike
- $X^{N,i}$ = membrane potential of the neuron *i*

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Particle systems Point processes Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike
- $X^{N,i}$ = membrane potential of the neuron i
- drift $-\alpha x$ models "exponential loss"

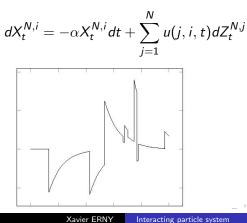
$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Introduction Paralization Paral

Particle systems Point processes Mathematical model

Neural network model

- particle = neuron
- a particle creates an event = a neuron sends a spike
- $X^{N,i}$ = membrane potential of the neuron *i*
- drift $-\alpha x$ models "exponential loss"



Large scale limit Linear scaling

Large scale limit

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

æ

Image: A mathematical states and a mathem

Large scale limit Linear scaling

Large scale limit

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Study the limit $N \to \infty \Longrightarrow$ rescale the sum :

< ≣ → 9 / 21 э

Large scale limit Linear scaling

Large scale limit

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Study the limit $N \to \infty \Longrightarrow$ rescale the sum :

- linear scaling N^{-1} (LLN) :
 - [Delattre et al. (2016)] (Hawkes process, u(j, i, t) = 1), [Chevallier et al. (2019)] (u(j, i, t) = u(j, i)), [Lick where the Ditlement (2017)] (u(i, i, t) = 1) multiment
 - [Löcherbach, Ditlevsen (2017)] (u(j, i, t) = 1, multi-population)

Large scale limit Linear scaling

Large scale limit

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Study the limit $N \to \infty \Longrightarrow$ rescale the sum :

linear scaling N⁻¹ (LLN) : [Delattre et al. (2016)] (Hawkes process, u(j, i, t) = 1), [Chevallier et al. (2019)] (u(j, i, t) = u(j, i)), [Löcherbach, Ditlevsen (2017)] (u(j, i, t) = 1, multi-population)
diffusive scaling N^{-1/2} (CLT) : random and centered u(j, i, t) [E. et al. (2019)], [E. et al. (a) (2021)], [Pfaffelhuber et al. (2021)], [E. et al. (b) (2021)]

Large scale limit Linear scaling

Large scale limit

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \sum_{j=1}^N u(j,i,t) dZ_t^{N,j}$$

Study the limit $N \to \infty \Longrightarrow$ rescale the sum :

linear scaling N⁻¹ (LLN) : [Delattre et al. (2016)] (Hawkes process, u(j, i, t) = 1), [Chevallier et al. (2019)] (u(j, i, t) = u(j, i)), [Löcherbach, Ditlevsen (2017)] (u(j, i, t) = 1, multi-population)
diffusive scaling N^{-1/2} (CLT) : random and centered u(j, i, t) [E. et al. (2019)], [E. et al. (a) (2021)], [Pfaffelhuber et al. (2021)], [E. et al. (b) (2021)]

Why making $N \to \infty$:

- it is natural $N \approx 86.10^9$
- the limit system can be easier to simulate and study

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Xavier ERNY Interacting particle system

10/21

æ

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Dynamic of $X^{N,i}$:

10/21

æ

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Dynamic of $X^{N,i}$: • $X_t^{N,i} = X_s^{N,i} e^{-\alpha(t-s)}$ if the system does not jump in [s, t[

10/21

∃ ► < ∃ ►</p>

э

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Dynamic of $X^{N,i}$: • $X_t^{N,i} = X_s^{N,i} e^{-\alpha(t-s)}$ if the system does not jump in [s, t[• $X_t^{N,i} = X_{t-}^{N,i} + \frac{1}{N}$ if any neuron emits a spike at t

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Dynamic of $X^{N,i}$: • $X_t^{N,i} = X_s^{N,i} e^{-\alpha(t-s)}$ if the system does not jump in [s, t[• $X_t^{N,i} = X_{t-}^{N,i} + \frac{1}{N}$ if any neuron emits a spike at t= $X_t^{N,i} = X_{t-}^{N,i} + \frac{1}{N}$ if any neuron emits a spike at t

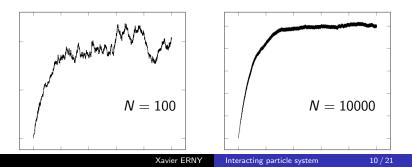
• the jump rate of $X^{N,i}$ is $\sum_{j=1}^{N} f(X_t^{N,j})$

Large scale limit Linear scaling

Model

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Dynamic of $X^{N,i}$: • $X_t^{N,i} = X_s^{N,i} e^{-\alpha(t-s)}$ if the system does not jump in [s, t[• $X_t^{N,i} = X_{t-}^{N,i} + \frac{1}{N}$ if any neuron emits a spike at t• the jump rate of $X^{N,i}$ is $\sum_{i=1}^{N} f(X_t^{N,j})$



Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

11/21

æ

E ► < E ►</p>

Image: A mathematical states and a mathem

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{X}_t^i = -\alpha \bar{X}_t^i dt + \lim_{N \to \infty} \frac{1}{N} \sum_{j=1}^N d\bar{Z}_t^j$$

æ

E ► < E ►</p>

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}^i_t = -lphaar{X}^i_t dt + \lim_{N o \infty} rac{1}{N} \sum_{j=1}^N dar{Z}^j_t$$

Fact (LLN) : if $(X_j)_{j \in \mathbb{N}^*}$ are iid with 1st order moment,

$$\frac{1}{N}\sum_{j=1}^{N}X_{j} \xrightarrow[N \to \infty]{a.s. \text{ and } L^{1}} \mathbb{E}\left[X_{1}\right]$$

Xavier ERNY Inte

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}^i_t = -lphaar{X}^i_t dt + \lim_{N o \infty}rac{1}{N}\sum_{j=1}^N dar{Z}^j_t$$

Fact (LLN) : if $(X_j)_{j \in \mathbb{N}^*}$ are iid with 1st order moment,

$$\frac{1}{N}\sum_{j=1}^{N}X_{j} \xrightarrow[N \to \infty]{a.s. \text{ and } L^{1}} \mathbb{E}\left[X_{1}\right]$$

Xavier ERNY Inter

≣ ► < ≣ ► 11 / 21

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{X}_{t}^{i} = -\alpha \bar{X}_{t}^{i} dt + \mathbb{E}\left[d\bar{Z}_{t}^{i}\right]$$

Fact (LLN) : if $(X_j)_{j \in \mathbb{N}^*}$ are iid with 1st order moment,

$$\frac{1}{N}\sum_{j=1}^{N}X_{j} \xrightarrow[N \to \infty]{a.s. \text{ and } L^{1}} \mathbb{E}\left[X_{1}\right]$$

Xavier ERNY Interacting particle system

le system

11/21

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{X}_{t}^{i} = -\alpha \bar{X}_{t}^{i} dt + \mathbb{E}\left[d\bar{Z}_{t}^{i}\right]$$

Fact (LLN) : if $(X_j)_{j \in \mathbb{N}^*}$ are iid with 1st order moment,

$$\frac{1}{N}\sum_{j=1}^{N}X_{j} \xrightarrow[N \to \infty]{a.s. \text{ and } L^{1}} \mathbb{E}\left[X_{1}\right]$$

Xavier ERNY Interacting particle system

le system

11/21

Large scale limit Linear scaling

Limit system (1)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{X}_t^i = -\alpha \bar{X}_t^i dt + \mathbb{E}\left[f(\bar{X}_t^i)\right] dt$$

Fact (LLN) : if $(X_j)_{j \in \mathbb{N}^*}$ are iid with 1st order moment,

$$\frac{1}{N}\sum_{j=1}^{N}X_{j} \xrightarrow[N \to \infty]{a.s. \text{ and } L^{1}} \mathbb{E}\left[X_{1}\right]$$

Xavier ERNY Interaction

Interacting particle system

∃ ► < ∃ ► 11 / 21

Large scale limit Linear scaling

Limit system (2)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{x}_t^i = -\alpha \bar{x}_t^i dt + f(\bar{x}_t^i) dt$$

< □ > < 同 >

▶ < ∃ >

æ

Large scale limit Linear scaling

Limit system (2)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

SDE driven by N point processes ($N \gg 1$)

Limit system

$$d\bar{x}_t^i = -\alpha \bar{x}_t^i dt + f(\bar{x}_t^i) dt$$

ODE

12/21

Large scale limit Linear scaling

Limit system (2)

N-neuron system

$$dX_t^{N,i} = -\alpha X_t^{N,i} dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

SDE driven by N point processes (N >>> 1)

Limit system

$$d\bar{x}_t^i = -\alpha \bar{x}_t^i dt + f(\bar{x}_t^i) dt$$

ODE

Result

$$\mathbb{E}\left[\sup_{0\leq s\leq t}\left|X_{s}^{N,i}-\bar{x}_{s}^{i}\right|\right]\leq C_{t}\cdot N^{-1/2}$$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

< ≣ ► 13 / 21 э

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough,

$$A^{N}g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_{t}^{N}) | X_{0}^{N} = x \right] - g(x) \right)$$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough,

$$A^{N}g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_{t}^{N}) | X_{0}^{N} = x \right] - g(x) \right)$$
$$A^{N}g(x) = -\alpha x g'(x) + Nf(x) \left[g\left(x + \frac{1}{N} \right) - g(x) \right]$$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough,

$$A^{N}g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_{t}^{N}) | X_{0}^{N} = x \right] - g(x) \right)$$
$$A^{N}g(x) = -\alpha x g'(x) + Nf(x) \underbrace{ \left[g \left(x + \frac{1}{N} \right) - g(x) \right]}_{\frac{1}{N}g'(x) + O(1/N^{2})}$$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough, $A^N g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_t^N) | X_0^N = x \right] - g(x) \right)$ $A^N g(x) = -\alpha x g'(x) + N f(x) \underbrace{ \left[g \left(x + \frac{1}{N} \right) - g(x) \right] }_{\frac{1}{N} g'(x) + O(1/N^2)}$ $N \longrightarrow +\infty$: $\bar{A}g(x) = -\alpha x g'(x) + f(x)g'(x)$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough, $A^N g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_t^N) | X_0^N = x \right] - g(x) \right)$ $A^N g(x) = -\alpha x g'(x) + N f(x) \underbrace{ \left[g \left(x + \frac{1}{N} \right) - g(x) \right] }_{\frac{1}{N} g'(x) + O(1/N^2)}$ $N \longrightarrow +\infty : \bar{A}g(x) = -\alpha x g'(x) + f(x)g'(x)$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough, $A^N g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_t^N) | X_0^N = x \right] - g(x) \right)$ $A^N g(x) = -\alpha x g'(x) + N f(x) \left[g \left(x + \frac{1}{N} \right) - g(x) \right] \frac{1}{N} g'(x) + O(1/N^2)$ $N \longrightarrow +\infty$: $\bar{A}g(x) = -\alpha x g'(x) + f(x) g'(x)$

$$\mathsf{d}\overline{x}_t = -\alpha \overline{x}_t dt + f(\overline{x}_t) dt$$

Large scale limit Linear scaling

Sketch of proof

$$\mathsf{dX}_t^N = -\alpha X_t^N dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

where $Z^{N,j}$ has rate $f(X_t^N)$

Infinitesimal generator of X^N : for g smooth enough, $A^{N}g(x) = \lim_{t \to 0} \frac{1}{t} \left(\mathbb{E} \left[g(X_{t}^{N}) | X_{0}^{N} = x \right] - g(x) \right)$ $A^{N}g(x) = -\alpha xg'(x) + Nf(x) \left[g\left(x + \frac{1}{N}\right) - g(x)\right]$ $\frac{1}{N}g'(x) + O(1/N^2)$ $N \longrightarrow +\infty$: $\bar{A}g(x) = -\alpha xg'(x) + f(x)g'(x)$ $\mathrm{d}\overline{x}_t = -\alpha \overline{x}_t dt + f(\overline{x}_t) dt$ $\left|\bar{A}g(x) - A^N g(x)\right| \leq \frac{1}{2N} f(x) ||g''||_{\infty}$ Xavier ERNY Interacting particle system 13/21

McKean-Vlasov frame Multi-population system

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$

14 / 21

э

∃ ► < ∃ ►</p>

< A >

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$dX_{t}^{N,i} = b(X_{t}^{N,i}, \mu_{t}^{N})dt + \sum_{j=1}^{N} u(j, i, t, \mu_{t}^{N})dZ_{t}^{N,j}$$
with $\mu_{t}^{N} := \frac{1}{N} \sum_{k=1}^{N} \delta_{X_{t}^{N,k}}$

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$dX_{t}^{N,i} = b(X_{t}^{N,i}, \mu_{t}^{N})dt + \sum_{j=1}^{N} u(j, i, t, \mu_{t}^{N})dZ_{t}^{N,j}$$
with $\mu_{t}^{N} := \frac{1}{N} \sum_{k=1}^{N} \delta_{X_{t}^{N,k}}$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$dX_{t}^{N,i} = b(X_{t}^{N,i}, \mu_{t}^{N})dt + \sum_{j=1}^{N} u(j, i, t, \mu_{t}^{N})dZ_{t}^{N,j}$$
with $\mu_{t}^{N} := \frac{1}{N} \sum_{k=1}^{N} \delta_{X_{t}^{N,k}}$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

Why it is natural :

$$dx_t^{N,i} = \frac{1}{N} \sum_{j=1}^N b(x_t^{N,j}, x_t^{N,i}) dt$$
Xavier ERNY
Interacting particle system
14/21

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$dX_{t}^{N,i} = b(X_{t}^{N,i}, \mu_{t}^{N})dt + \sum_{j=1}^{N} u(j, i, t, \mu_{t}^{N})dZ_{t}^{N,j}$$
with $\mu_{t}^{N} := \frac{1}{N} \sum_{k=1}^{N} \delta_{X_{t}^{N,k}}$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

Why it is natural :

$$dx_t^{N,i} = \frac{1}{N} \sum_{j=1}^N b(x_t^{N,j}, x_t^{N,i}) dt$$
Xavier ERNY Interacting particle system 14/21

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$\begin{split} dX^{N,i}_t &= b(X^{N,i}_t,\mu^N_t)dt + \sum_{j=1}^N u(j,i,t,\mu^N_t)dZ^{N,j}_t \\ \text{with } \mu^N_t &:= \frac{1}{N}\sum_{k=1}^N \delta_{X^{N,k}_t} \end{split}$$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

Why it is natural :

$$dx_t^{N,i} = \int_{\mathbb{R}} b(y, x_t^{N,i}) d\mu_t^N(y) dt$$

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$\begin{split} dX^{N,i}_t &= b(X^{N,i}_t,\mu^N_t)dt + \sum_{j=1}^N u(j,i,t,\mu^N_t)dZ^{N,j}_t \\ \text{with } \mu^N_t &:= \frac{1}{N}\sum_{k=1}^N \delta_{X^{N,k}_t} \end{split}$$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

Why it is natural :

$$dx_t^{N,i} = \int_{\mathbb{R}} b(y, x_t^{N,i}) d\mu_t^N(y) dt$$

McKean-Vlasov system : definition

McKean-Vlasov equation :

$$dX_t = b(X_t, \mu_t)dt + u(X_t, \mu_t)dZ_t$$

with $\mu_t := \mathcal{L}(X_t)$ McKean-Vlasov system :

$$dX_{t}^{N,i} = b(X_{t}^{N,i}, \mu_{t}^{N})dt + \sum_{j=1}^{N} u(j, i, t, \mu_{t}^{N})dZ_{t}^{N,j}$$
with $\mu_{t}^{N} := \frac{1}{N} \sum_{k=1}^{N} \delta_{X_{t}^{N,k}}$

First inspiration :

Boltzmann equation kinetic theory of gases [Kac (1956)]

Why it is natural :

$$dx_t^{N,i} = \tilde{b}(\mu_t^N, x_t^{N,i})dt$$

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

15 / 21

æ

< ロ > < 回 > < 回 > < 回 > < 回 >

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}_t^i = b(ar{X}_t^i,ar{\mu}_t)dt + \mathbb{E}\left[f(ar{X}_t^i)
ight]dt$$

with

$$\bar{\mu}_t = \lim_N \frac{1}{N} \sum_{k=1}^N \delta_{\bar{X}_t^k} =$$

э

E ► < E ►</p>

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}_t^i = b(ar{X}_t^i,ar{\mu}_t)dt + \mathbb{E}\left[f(ar{X}_t^i)
ight]dt$$

with

$$\bar{\mu}_t = \lim_N \frac{1}{N} \sum_{k=1}^N \delta_{\bar{X}_t^k} = \mathbb{E} \left[\delta_{\bar{X}_t^i} \right] =$$

э

E ► < E ►</p>

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}^i_t = b(ar{X}^i_t,ar{\mu}_t)dt + \mathbb{E}\left[f(ar{X}^i_t)
ight]dt$$

with

$$\bar{\mu}_t = \lim_N \frac{1}{N} \sum_{k=1}^N \delta_{\bar{X}_t^k} = \mathbb{E} \left[\delta_{\bar{X}_t^i} \right] = \mathcal{L}(\bar{X}_t^i)$$

э

E ► < E ►</p>

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$d\bar{X}_t^i = b(\bar{X}_t^i, \bar{\mu}_t)dt + \mathbb{E}\left[f(\bar{X}_t^i)\right]dt$$

with

$$\bar{\mu}_t = \lim_N \frac{1}{N} \sum_{k=1}^N \delta_{\bar{X}_t^k} = \mathbb{E} \left[\delta_{\bar{X}_t^i} \right] = \mathcal{L}(\bar{X}_t^i)$$

э

E ► < E ►</p>

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N)dt + \frac{1}{N}\sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}_t^i = b(ar{X}_t^i,ar{\mu}_t)dt + \int_{\mathbb{R}} f(y)dar{\mu}_t(y)dt$$

with

$$\bar{\mu}_t = \lim_N \frac{1}{N} \sum_{k=1}^N \delta_{\bar{X}_t^k} = \mathbb{E} \left[\delta_{\bar{X}_t^i} \right] = \mathcal{L}(\bar{X}_t^i)$$

< □ > < / >

э

E ► < E ►</p>

McKean-Vlasov frame Multi-population system

McKean-Vlasov linear limit

N- particle system

$$dX_t^{N,i} = b(X_t^{N,i}, \mu_t^N) dt + \frac{1}{N} \sum_{j=1}^N dZ_t^{N,j}$$

Limit system

$$dar{X}^i_t = b(ar{X}^i_t,ar{\mu}_t)dt + \int_{\mathbb{R}} f(y)dar{\mu}_t(y)dt$$

with

$$\bar{\mu}_t = \lim_{N} \frac{1}{N} \sum_{k=1}^{N} \delta_{\bar{X}_t^k} = \mathbb{E} \left[\delta_{\bar{X}_t^i} \right] = \mathcal{L}(\bar{X}_t^i)$$

Result [Andreis et al. (2018)] (and [E. (2021)])

$$\mathbb{E}\left[\sup_{0\leq s\leq t}\left|X_{s}^{N,i}-\bar{X}_{s}^{i}\right|\right]\leq C_{t}\cdot N^{-1/2}$$

< E > < E >

McKean-Vlasov frame Multi-population system

Multi-population frame

Previously : all the particles within a system are similar

▶ < ≣ > 16 / 21 э

Multi-population frame

Previously : all the particles within a system are similar

Now :

- consider a system divided into a fix number of subsystems
- all the particles within a subsystem are similar

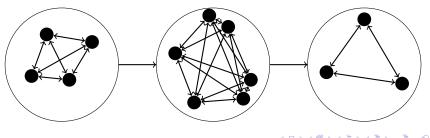
Multi-population frame

Previously : all the particles within a system are similar

Now :

- consider a system divided into a fix number of subsystems
- all the particles within a subsystem are similar

Example : neural retina



McKean-Vlasov frame Multi-population system

Multi-population model

• *N* = total number of particles

Xavier ERNY Interacting particle system

▶ ◀ \= ▶
17 / 21

< 4 → <

э

McKean-Vlasov frame Multi-population system

Multi-population model

- N = total number of particles
- *K* = number of subsystems

McKean-Vlasov frame Multi-population system

Multi-population model

- N = total number of particles
- K = number of subsystems
- N_k = number of particles in susbsystem k

(i.e.
$$N = N_1 + N_2 + ... + N_K$$
)

McKean-Vlasov frame Multi-population system

Multi-population model

- N = total number of particles
- K = number of subsystems
- N_k = number of particles in susbsystem k (i.e. $N = N_1 + N_2 + ... + N_K$)
- for each k, $N_k/N \xrightarrow[N \to \infty]{} \lambda_k > 0$

.⊒ →

Multi-population model

- N = total number of particles
- K = number of subsystems
- N_k = number of particles in susbsystem k (i.e. $N = N_1 + N_2 + ... + N_K$)
- for each k, $N_k/N \xrightarrow[N \to \infty]{} \lambda_k > 0$
- I(k) = the set of subsystems that "sends" jumps to the subsystem k

McKean-Vlasov frame Multi-population system

Multi-population model

- N = total number of particles
- *K* = number of subsystems
- N_k = number of particles in susbsystem k (i.e. $N = N_1 + N_2 + ... + N_K$)
- for each k, $N_k/N \xrightarrow[N \to \infty]{} \lambda_k > 0$
- I(k) = the set of subsystems that "sends" jumps to the subsystem k

$$dX_t^{N,k,i} = b_k(X_t^{N,k,i})dt + \sum_{k' \in I(k)} \sum_{j=1}^{N_{k'}} u_{k',k}(t)dZ_t^{N,l,j}$$

References (1)

Examples :

- Löcherbach, Ditlevsen (2017). Multi-class oscillating systems of interacting neurons. Stoch. Proc. Appl.
- Reynaud-Bouret, Schbath (2010). Adaptive estimation for Hawkes processes; application to genome analysis. The Annals of Statistics.
- Stomakhin, Short, Bertozzi (2011). Reconstruction of missing data in social networks based on temporal patterns of interactions. Inverse Problems.
- Kac (1956). Foundations of kinetic theory. Proceedings of the third Berkeley Symposium on mathematical statistics and probability.

Thinning algorithm :

- Lewis, Schedler (1979). Simulation of nonhomogeneous Poisson process by thinning. Naval Res. Logistics Quart.
- Ogata (1981). On Lewis' simulation method for point processes. IEEE Trans. Inform. Theory.

References (2)

Linear large scale limits :

- Löcherbach, Ditlevsen (2017). Multi-class oscillating systems of interacting neurons. Stoch. Proc. Appl.
- Delattre, Fournier, Hoffman (2016). Hawkes processes on large networks. Ann. Appl. Probab.
- Chevallier, Duarte, Löcherbach, Ost (2019). Mean field limit for non linear spatially extended Hawkes processes with exponential memory kernels. Stoch. Proc. Appl.
- Andreis, Dai Pra, Fischer (2018). McKean-Vlasov limit for interacting systems with simultaneous jumps. Stoch. Proc. Appl.
- E. (2021). Well-posedness and propagation of chaos for McKean-Vlasov equations with jumps and locally Lipschitz coefficients. ArXiv.

ヨトイヨト

References (3)

Diffusive large scale limits :

- E., Löcherbach, Loukianova (2019). Mean field limits for interacting Hawkes processes in a diffusive regime. Accepted at Bernoulli.
- E., Löcherbach, Loukianova (a) (2021). Conditional propagation of chaos for mean field systems of interacting neurons. Electron. J. Probab.
- Pfaffelhuber, Rotter, Stiefel (2021). Mean-field limits for non-linear Hawkes processes with excitation and inhibition. ArXiv.
- E., Löcherbach, Loukianova (b) (2021). White-noise driven conditional McKean-Vlasov limits for systems of particles with simultaneous and random jumps. ArXiv.

∃ ► < ∃ ►</p>

Thank you for your attention !

Questions?

Xavier ERNY Interacting particle system

▶ ◀ \= ▶
21 / 21

æ